

# The Power of Proofs: New Algorithms for Timed Automata Model Checking

**Peter Fontana** and Rance Cleaveland

Department of Computer Science

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UNIVERSITY OF  
MARYLAND

# Goal: Automatic Verification with Timing Constraints

**Formally verify** program correctness

**Automate** the verification

Handle **time and timing constraints**, both in model and specification

# Timing Constraints Exist: Model Constraints



We allow the train to wait for different amounts of time

The gate takes time to lower

# Timing Constraints Exist: Specification Constraints



The gate will be up within 2 minutes after a train leaves

Any train is in the region is in the region for at most 4 minutes

# Our Framework

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Programs modeled with **timed automata**

Properties specified with a **timed mu-calculus** (a modal logic)

# Tool Implementation Exists

**Peter Fontana** and Rance Cleaveland. *On-The-Fly Timed Automata Model Checking*. Presented at CMACS PI Meeting on May 16, 2013

# The Power of Proofs

This tool generates a **mathematical proof**

Verification using **proof rules**

We optimize performance by using **derived**  
proof rules

# The Trick: Memoization

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“Those who cannot remember the past are condemned to repeat it” (George Santayana)



# The Trick: Memoization

Fibonacci Series:  $a_0 = 1, a_1 = 1, a_n = a_{n-2} + a_{n-1}$

Compute  $a_4$ :

$$a_4 = \mathbf{a_2} + a_3$$

$$\mathbf{a_2} = a_1 + a_0 = 1 + 1 = 2$$

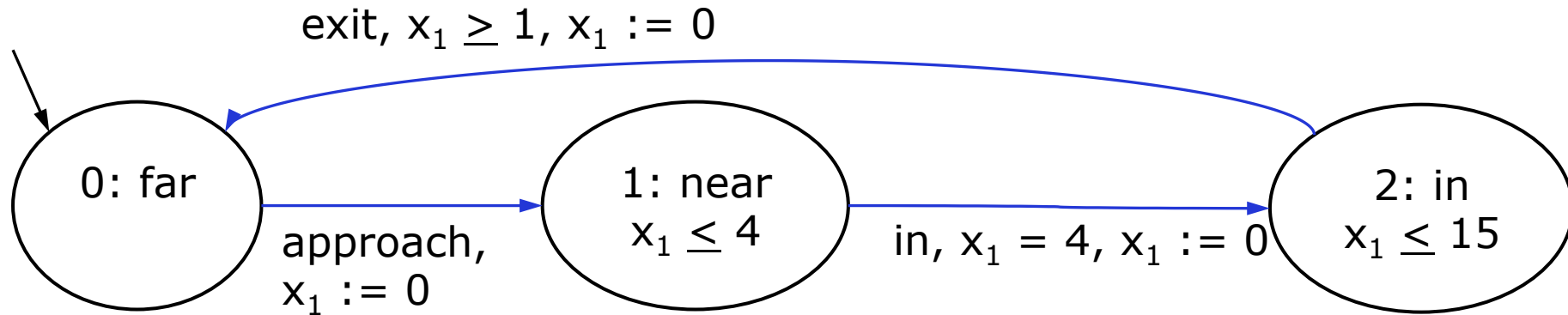
**Memoization: Store "a2 = 2"**

$$a_4 = 2 + a_3$$

$$a_4 = 2 + (a_2 + a_1)$$

# The Details

# Model: Timed Automata (State Machine + Clocks) [AD94]



Alur-Dill Model: timing constraints use clocks

A **state** is a **(location, clock values)** pair

# Specification: Timed Modal Mu-Calculus $L_{\nu, \mu}^{\text{rel}}$

Boolean Logic

Variables  $X_i$

Action Modalities  $[a](\varphi), \langle a \rangle(\varphi), [-](\varphi), \langle - \rangle(\varphi)$

Time Modalities  $\forall(\varphi), \exists(\varphi)$

Fixpoints  $\underline{\nu}, \underline{\mu}$

Relativized Time Modalities  $\forall_{\varphi_1}(\varphi_2), \exists_{\varphi_1}(\varphi_2)$

# Fixpoints

**Definition (Formal):** A **fixpoint** of a function  $f$  is a value  $x$  such that  $f(x) = x$

# The Power of Fixpoints: Writing Always Recursively

**Always p**: **p** is true now, and **Always p** is true in all next states.

$$X_1 \stackrel{v}{=} p \wedge \forall([ - ](X_1))$$

**Note:** This simplified formula assumes p only contains atomic propositions

# The Power of Fixpoints: Formulas Represent States

**Always p**: **p** is true now, and **Always p** is true in all next states.

$$X_1 \stackrel{v}{=} p \wedge \forall([\text{---}](X_1))$$

$X_1$  is a **set of states** computed by this formula

$$\text{Function } f: f(X_1) = p \wedge \forall([\text{---}](X_1))$$

# The Power of Fixpoints: Recursion as Local Search

**Always p**: **p** is true now, and **Always p** is true in all next states.

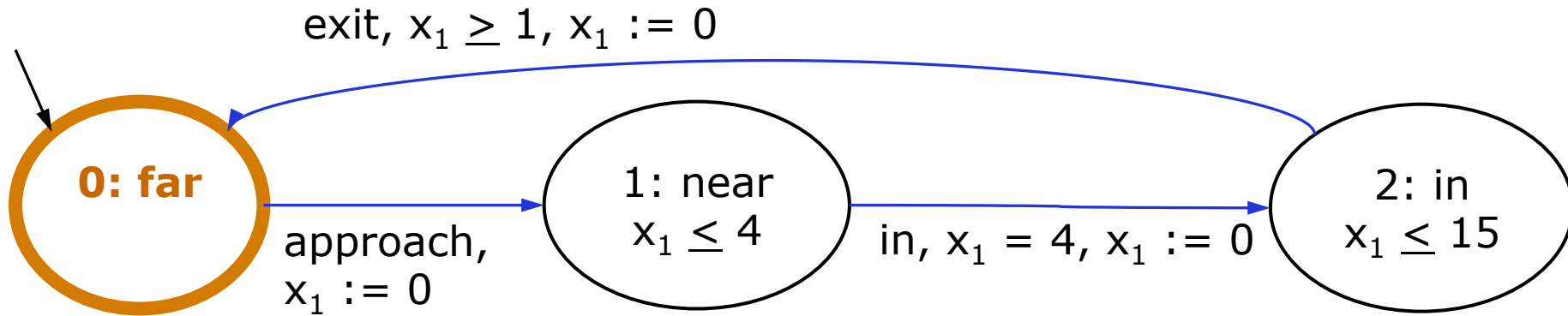
$$X_1 \stackrel{v}{=} p \wedge \forall([\text{---}](X_1))$$

1. Have  $X_1$  start at the initial state
2. Formula transitions  $X_1$  to all next states
3. Stop when  $X_1$  is a previously seen state

**Greatest Fixpoint (v)**: Visiting a previous state implies formula truth

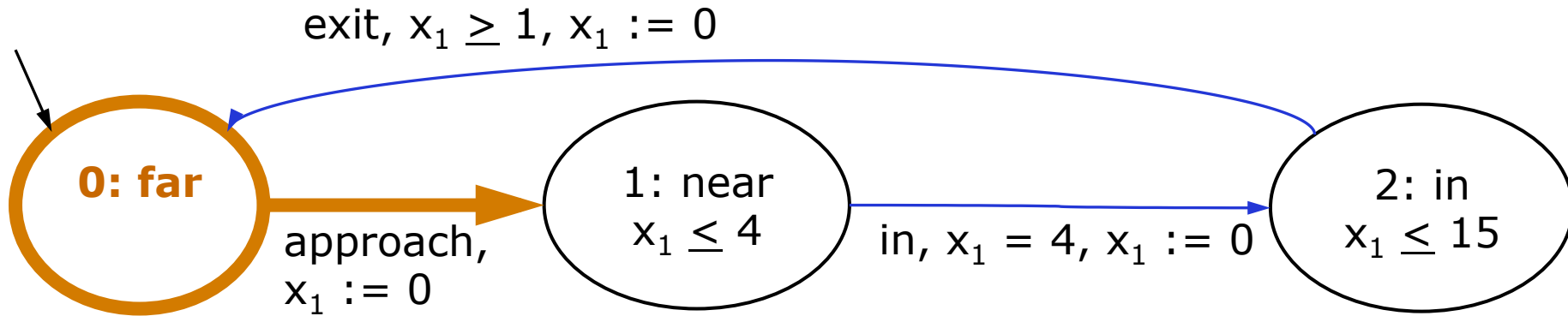


# The Power of Fixpoints: Never broken (AG)



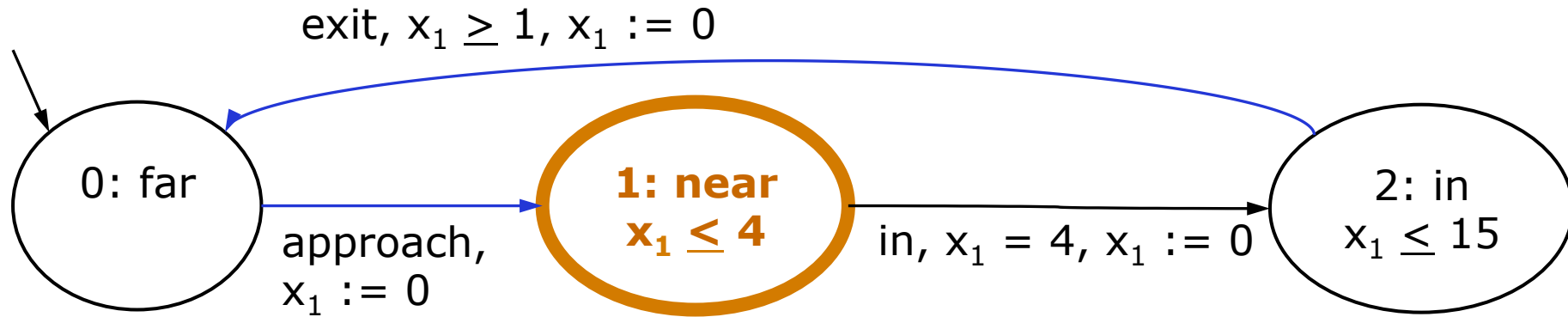
**Verifier:** Location **0: far** is not broken

# The Power of Fixpoints: Never broken (AG)



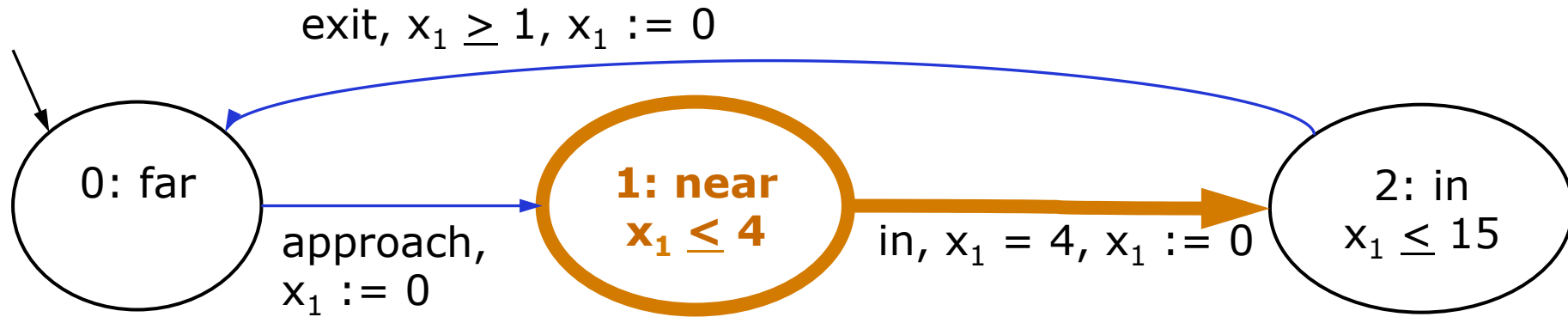
**Verifier:** Location **0: far** is not broken

# The Power of Fixpoints: Never broken (AG)



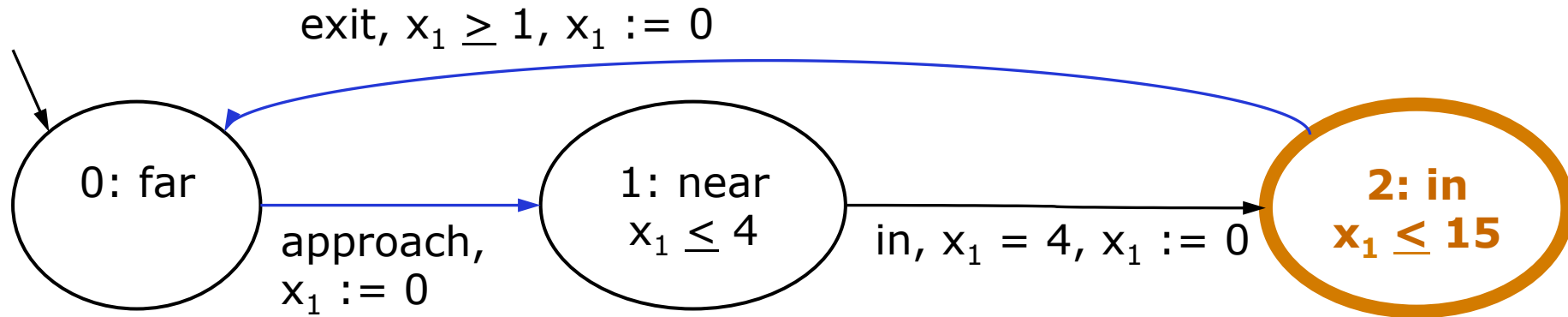
**Verifier:** Location **1: near** is not broken

# The Power of Fixpoints: Never broken (AG)



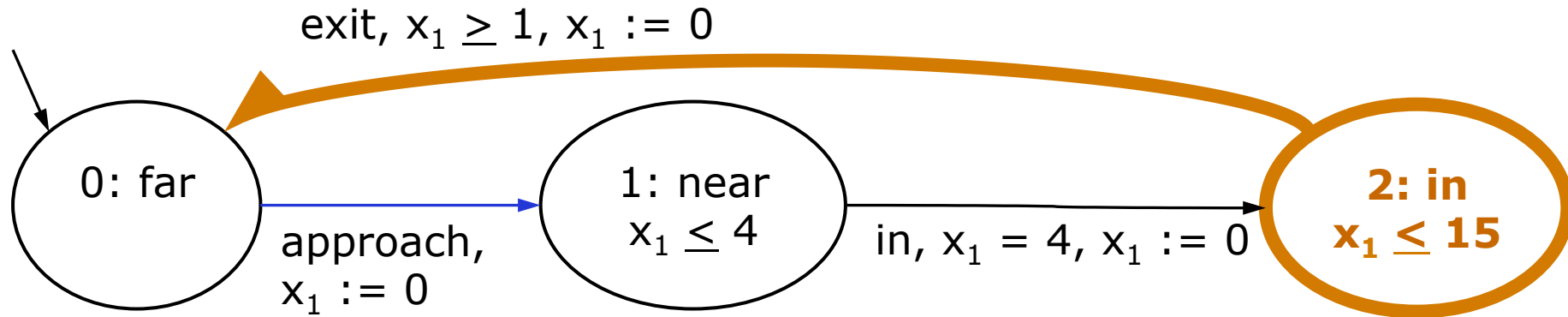
**Verifier:** Location **1: near** is not broken

# The Power of Fixpoints: Never broken (AG)



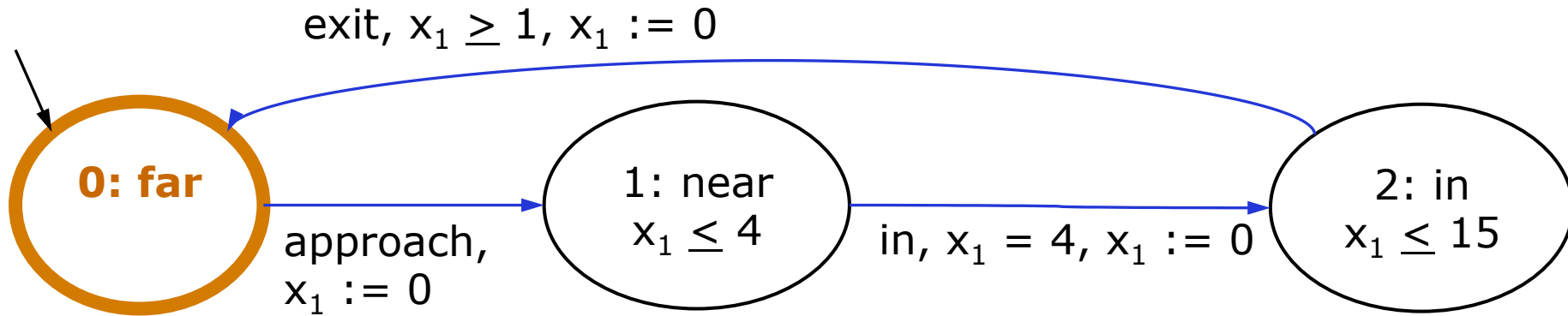
**Verifier:** Location **2: in** is not broken

# The Power of Fixpoints: Never broken (AG)



**Verifier:** Location **2: in** is not broken

# The Power of Fixpoints: Never broken (AG)



**Verifier:** We have visited **0: far** again (circularity);  
apply **greatest** fixpoint

# Proof Rules: One Step at A Time ( $X_1$ : Always not broken)

$$\frac{\text{Premise 1} \quad \dots \quad \text{Premise } n}{\text{Conclusion}} \text{ (Rule Name)}$$
$$(0 : \textit{far}, \{x_1 = 0\}) \vdash X_1 \quad \mathbf{True} \text{ (Greatest fixpoint)}$$

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$$(1 : \textit{near}, \{x_1 = 0\}) \vdash X_1$$

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$$(0 : \textit{far}, \{x_1 = 0\}) \vdash \neg \textit{broken} \wedge \text{all next states } X_1$$

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$$(0 : \textit{far}, \{x_1 = 0\}) \vdash X_1$$



# Relativization Operators

**Definition:**  $L_{v,\mu}^{\text{rel}}$  relativization operators are:

$\exists_{\varphi_1}(\varphi_2)$ : for all times  $\delta' < \delta$ ,  $\varphi_1$  is true

$\forall_{\varphi_1}(\varphi_2)$ :  $\varphi_1$  releases  $\varphi_2$  from being true

Definition by **duality**:  $\exists_{\varphi_1}(\varphi_2) \stackrel{\text{def}}{=} \neg \forall_{\neg \varphi_1}(\neg \varphi_2)$

Obtaining  $L_{v,\mu}$  operators:  $\exists_{\text{tt}}(\varphi), \forall_{\text{ff}}(\varphi)$

# Relativization Operators give Expressive Power

**Theorem:** We can express all of TCTL in  $L_{v,\mu}^{\text{rel}}$

# Relativization Operators?!?

## We Need Them!

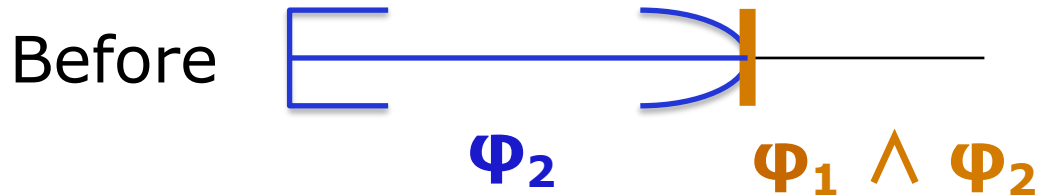
**Theorem:** We cannot express TCTL formula  $A\varphi_1R\varphi_2$  in  $L_{v,\mu}$

# Proof Rule Optimization 1: Relativized All

**Lemma:**  $\forall_{\varphi_1}(\varphi_2) \equiv \forall(\varphi_2) \vee \exists_{\varphi_2}(\varphi_1 \wedge \varphi_2)$

Use proof of derivation to generate a **derived rule**

# Relativized All Optimization: Rewrite a Subrule



$$\frac{\forall(\varphi_2) \vee \exists_{\leq \varphi_2}(\varphi_1)}{\forall(\varphi_2) \vee \exists_{\varphi_2}(\varphi_1 \wedge \varphi_2)} \frac{}{\forall_{\varphi_1}(\varphi_2)}$$

# Relativized All Optimization: Memoize $\varphi_2$

$$\forall(\boxed{\varphi_2}) \vee \exists_{\leq \boxed{\varphi_2}}(\varphi_1)$$

1. Find **all states** that satisfy  $\varphi_1$
2. Find **all states** that satisfy  $\varphi_2$
3. Reason with **memoized** stored states to handle logic operators  $\forall, \exists$

# Correctness of Proof Rules

**Theorem:** The proof rules (original and derived) are **sound** and **complete**.

# Conclusion

Implementation can check more specifications: the entire alternation-free fragment of  $L^{\text{rel}}$

Using derived proof rules optimizes performance



# Future Work

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Further Proof Utilization: Extra verification information

Performance optimization

